MARUDHAR KESARI JAIN COLLEGE FOR WOMEN, VANIYAMBADI PG & RESEARCH DEPARTMENT OF MATHEMATICS

CLASS : I B.Sc PHYSICS

SUBJECT CODE: MATHEMATICS I

SUBJECT NAME: 23UEMA10C

SYLLABUS

UNIT-II

Matrices

Symmetric – Skew-Symmetric – Hermitian – Skew – Hermitian – Orthogonal and Unitary matrices – Cayley - Hamilton theorem (without proof) – Verification - Computation of inverse of matrix using Cayley - Hamilton theorem.

Matrices

kind of matrice

we shall consider him square matrices. In these, the element in the ith row and ith column is denoted by aij. So the element in the leading diagonals are an azzrazziazziany

Real Matrix:

A matrix whose elements are real numbers is called a real matrix.

complex matrix:

A matrix in which atteast one element is imaginary is called a complex number.

Symmetric matrix:

A oquare matrix [aij] is said to be symmetric matrix of aij aji to all I and j that is, the element in ith row and ith column is equal to the element in the jth row and ith column

Explanation:

A Symmetric matrix is symmetrical about the diagnal. That is the image of an element in the reflection on the leading diagonal is the element it sets. $(A = A^T)$.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 1 \\ 3 & 1 & 3 \end{bmatrix}, A^{T} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 1 \\ 3 & 1 & 3 \end{bmatrix} A = A^{T}$$

 $Q_{11} = Q_{11} \qquad Q_{21} = Q_{12} \qquad Q_{31} = Q_{13}$ $Q_{12} = Q_{21} \qquad Q_{22} = Q_{22} \qquad Q_{32} = Q_{23}$ $Q_{13} = Q_{31} \qquad Q_{32} = Q_{32} \qquad Q_{33} = Q_{33}$

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}, \quad A^{T} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

 $A = A^{T} (0r)$ Q | 1 = Q | 1 Q | 1 = Q | 2 Q | 2 = Q | 2Q | 2 = Q | 2 Sums

O find the value of x1412, a which satisfies the matrix equation.

$$\begin{bmatrix} x+3 & 2y+x \\ z-1 & 4 \end{bmatrix} = \begin{bmatrix} 0 & -7 \\ 3 & 2a \end{bmatrix}$$

Given:

$$x+3=0$$
, $2y+x=-7$, $z-1=3$, $y=20$
 $x=-3$ $2y-3=-7$ $z=37$ $z=4$
 $y=-2$

Category and productions

Skew symmetrize matrix:

A square [aij] is said to be a skew symmetrix matrix of aij=-aji for all i and j, that is the element in the ith row and jth column is equal to the negative of the element. In the jth row and ith column.

Explanation:

In a skew symmetric matrix, the image of an element in the reflection on the leading diagonal is its hegative.

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$$A = \begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -8 & 0 \end{bmatrix}, A^{T} = \begin{bmatrix} 0 & -1 & -2 \\ 1 & 0 & -3 \\ 2 & 3 & 0 \end{bmatrix},$$

$$-A^{T} = \begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{bmatrix}$$

A = * T skew symmetric.

RESULT:

O Let the square matrix A is skow. Symmetric then aij = -aji. In this setting j=i, we get.

aii = -aii, aii + aii = 0

=+2 #0 then aii = 0 1 80 the leading diagonal elements are zero

@ 46 A is any square motrix 1 then by using matrix algebra we have.

$$A = \frac{1}{2} (AA) = \frac{1}{2} (A+A)$$

$$= \frac{1}{2} (A-A^T+A^T+A)$$

$$= (A - A^{T}) + (A + A^{T}).$$

$$= \frac{(A - A^{\dagger})}{2} \frac{(A + A^{\dagger})}{2}$$

An this $\frac{1}{2}$ (A+AT) is Symmetric $\Rightarrow \frac{1}{2}$ (A+AT) $\Rightarrow \frac{1}{2}$ (A+AT) $\Rightarrow \frac{1}{2}$ (A+AT) $\Rightarrow \frac{1}{2}$ (A+AT) $\Rightarrow \frac{1}{2}$ (AT+A)

ALLO = (A-AT) is skew symmetric

= (A-AT) = + = (A-AT) = + = (AT-(A))

 $= \frac{1}{2} (A^{T-}A) = -\frac{1}{2} (A^{-}A)$

Thus, the matrix A has been expressed as the sum of the symmetric matrix & (A+AT) and the steel symmetric matrix & (A+AT) and

(1) 46 A= [1 -1 2] prove that A+AT is symmetric and A-AT is skew-Symmetric.

Given:-

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 3 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix}, A^{T} \begin{bmatrix} 1 & 3 & 1 \\ -1 & 0 & -1 \\ 2 & 1 & 0 \end{bmatrix}$$

$$A + A^{T} = \begin{bmatrix} 1 & -1 & 27 \\ 3 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix} + \begin{bmatrix} 1 & 3 & 1 \\ -1 & 0 & -1 \\ 2 & 1 & 0 \end{bmatrix}$$

$$A + A^{T} = \begin{bmatrix} 2 & 2 & 3 \\ 2 & 0 & 0 \\ 3 & 0 & 0 \end{bmatrix}$$

$$(A+A)^{T} = \begin{bmatrix} 2 & 2 & 3 \\ 2 & 0 & 0 \\ 3 & 0 & 0 \end{bmatrix}^{T}$$

$$(A+A)^{T} = \begin{bmatrix} 2 & 2 & 3 \\ 2 & 0 & 0 \\ 3 & 0 & 0 \end{bmatrix}$$

. AT is Symmetric.

$$A - A^{T} = \begin{bmatrix} 1 & -1 & 2 \\ 3 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 1 \\ -1 & 0 & -1 \\ 2 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1-1 & -1-3 & 2-1 \\ -3-1 & 0-0 & 1-1 \\ 1-2 & -1-1 & 0-0 \end{bmatrix}$$

$$A - A^{T} = \begin{bmatrix} 0 & -4 & 1 \\ 4 & 0 & 2 \\ 1 & -2 & 0 \end{bmatrix}$$

$$(A-A^{T})^{T} = \begin{bmatrix} 0 & 4 & 17 \\ -4 & 0 & -2 \\ 1 & 2 & 0 \end{bmatrix}$$

AT is skew symmetric.

Hermitian:

* complex square matrix [aij] is
said to be an hermitian matrix it aij,
conjugate of aji or aij = aji torall
i and i.

TCA)=*A=A

Conjugate of a matrix: element sign drange

If A is a complex matrix, then
the matrix obtained from A by.

replacing its elements by their

conjugate is called conjugate of

A and is denoted by A.

$$A = \begin{bmatrix} 1+9 & 2+2i \\ 3-3i & 4-4i \end{bmatrix}$$

$$\overline{A} = \begin{bmatrix} 1 - i & 2 - 2i \\ 3 + 3i & 4 + 4i \end{bmatrix}$$

$$(\overline{A})^{T} = \begin{bmatrix} 1-i & 3+3i \\ 2-2i & 4-4i \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3-i \\ 3+i & 4 \end{bmatrix}$$

 $a_{11} = a_{11}$ $a_{12} = 3t^{1}$ $a_{21} = 3t^{1}$ $a_{21} = 3t^{1}$

$$A^* = (\overline{A})^T = \begin{bmatrix} 1 & 3-i \\ 3+i & 4 \end{bmatrix}$$

3000

@ Ib A is homitian Matrix, then IT-A theij = aji, Replacing j by i, we get aii = aii or aii is real. that is, in a hermitian matrix, the diagonal clements are all real.

i=i aii = aii aii = atib of aii=a aii = a-ib.

atib = a-ib $\dot{y}b = -\dot{x}b$

b = -b

b+b=0

-: A is a real number.

Note:
$$(A)^T$$
 = A $[(A)^T]^+ = A^T$

1 H A is a hermitian matrix, then (A)T = A and SET[CA)T]T = AT (OT) A = A

Any hermitian matrix can be writtens A= = (A+A)+1/2 (A-A)

(De)

$$= \frac{1}{2} (A + \overline{A}) + i (\frac{1}{2} (\overline{A} - A)] = R + ig$$

$$= \frac{1}{2} (A + \overline{A})$$

$$S = \frac{1}{2} (\overline{A} - A)$$

$$S = \frac{1}{2} (\overline{A} - A)$$

R is real and Symmetric matrix for real.

$$R = \frac{1}{2} (A + \overline{A})$$

$$R = \frac{1}{2} (A + \overline{A}) = \frac{1}{2} (A + \overline{A})$$

$$R = \frac{1}{2} (A + \overline{A}) + \frac{1}{2} (A + \overline{A})$$

$$R = \frac{1}{2} (A + \overline{A}) + \frac{1}{2} (A + \overline{A})$$

for symmetric

$$R^{T} = \frac{1}{2} (A + \overline{A})^{T}$$

$$= \frac{1}{2} (A^{T} + (\overline{A})^{T})$$

$$= \frac{1}{2} (A^{T} + A^{*}) = \frac{1}{2} (A^{T} + A)$$

$$= \frac{1}{2} (\overline{A} + A)$$

RT=R R is a symmetric matrix and Real 1.

S is a real and Skew-symmetric for real $(S=\overline{S})$

be writtens as sum of creal symmetric) and real, skew symmetric matrix in the

3 of A is real and symmetric matrix then $\vec{A} = \vec{A}$ and $\vec{A}^T = \vec{A} \cdot \vec{S} \circ (\vec{A})^T = \vec{A}^T \vec{A}$ that is a hermitian matrix, thus every symmetric matrix is a hermitian matrix is a hermitian matrix. But the converse hermitian matrix. But the converse heed not be the.

Eg: [1-11] is a hermitian matrix
but not a symmetric
Matrix.

Skew Hermitian Matrix:

is said to be a skew - Hermitiani, and aij = -aji.

Example:

$$A = \begin{bmatrix} i & 3+i \\ -3+i & 2i \end{bmatrix}, A = \begin{bmatrix} -i & 3-i \\ -3-i & -2i \end{bmatrix}$$

$$(\overline{A})^{T} = \begin{bmatrix} -i & -3 - i \\ 3 - i & -2i \end{bmatrix}, -(\overline{A})^{T} = \begin{bmatrix} i & 3 + i \\ -3 + i & 2i \end{bmatrix}$$

 $A = -(\bar{A})^T A is a skew$ Hermitian matrix

REGULT:

Then ail is puvely imaginary

Skew Hermitian.

Replace i=j = t aii = -aii aii = a + ib, aii = a - ib. a + ib = -(a - ib) a + ib = -a + ib a = -a

a = 0

aii = iib + then aii is purely imaginary

imaginary.

NOTE:

1) It A is a hermitian matrix. Then it is a skew-hermitian matrix.

Hermitian.

T(A) = A

Let B=iA, $\overline{B}=(\overline{iA})=-i\overline{A}$ $(\overline{B})^{T}=(-i\overline{A})^{T}=-i(\overline{A})^{T}$ $(\overline{B})^{T}=-i\overline{A}=-i\overline{A}$ $(\overline{B})^{T}=-i\overline{A}$ $-(\overline{B})^{T}=-i\overline{A}$, $-(\overline{B})^{T}=B$.

B is skew hermitian it is oken Hermitian.

46 A is real and skew symmetric Matrix, then $\overline{A} = A$ and $A^T = -A$ let real $A = \overline{A}$

Skew symmetric

$$A = -A^{T}$$

$$= -A = A^{T}$$

by matrix Algebra. we have.

$$A = \frac{1}{2} (2A) = \frac{1}{2} (A + A) = \frac{1}{2} (A + A)^{2}$$

$$- (A)^{T} + A).$$

In this matrix 1/2 (A+(A)T) is a hermitian matrix because we have.

To prove hermitian

$$B = \frac{1}{2} (A + (\overline{A})^{T})$$

$$\overline{B} = \frac{1}{2} (\overline{A} + (\overline{A})^{T})$$

$$= \frac{1}{2} (\overline{A} + (\overline{A})^{T})$$

$$= \frac{1}{2} (\overline{A} + (\overline{A})^{T})$$

$$= \frac{1}{2} (\overline{A} + A^{T})$$

$$\Rightarrow (\overline{B})^{T} = \frac{1}{2} (\overline{A} + \overline{A}^{T})^{T}$$

$$= \frac{1}{2} ((\overline{A})^{T} + (\overline{A}^{T})^{T}).$$

$$= \frac{1}{2} (\overline{A})^{T} + A)$$

$$(\overline{B})^{T} = B$$

- (/2(A + (Ā)T) is an homitian Metrix. And the Matrix

1/2 (A-(A)T) is a Skew-heamitian

Matrix because.

$$C = \frac{1}{2} (A - (\overline{A})^{T})$$

$$= \frac{1}{2} (\overline{A} - (\overline{A})^{T})$$

$$= \frac{1}{2} (\overline{A} - (\overline{A})^{T})$$

$$= \frac{1}{2} (\overline{A} - A^{T})$$

$$= \frac{1}{2} (\overline{A} - A^{T})$$

$$= \frac{1}{2} (\overline{A})^{T} - (A^{T})^{T}$$

$$= \frac{1}{2} (A^{T} - A^{T})$$

$$= \frac{1}{2} (A^{T} - A^{T})^{T}$$

$$= \frac{1}{2} (A^{T} - A^{T})^{T}$$

$$= \frac{1}{2} (A^{T} - A^{T})^{T}$$

$$\Rightarrow \frac{1}{2} (A^{T} - A^{T})^{T}$$

hermitian matrix.

Any square matrix can be written as sum of hermitian and strew-hermitian matrix.

orthogonal Matrix:

A square notix is called an or thogonal matrix is $AA^{\dagger} = A^{\dagger}A = I$

Ex:-

(3)
$$A = \begin{bmatrix} \cos 0 & \sin 0 & 0 \\ -\sin 0 & \cos 0 & 0 \end{bmatrix} = + +^{\top} = \begin{bmatrix} \cos 0 & -\sin 0 & 0 \\ \sin 0 & \cos 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \cos^2\theta + \sin^2\theta + 0 & -\cos\theta \sin\theta + \cos\theta \sin\theta + \cot\theta \\ -\cos\theta \sin\theta + \cos\theta \sin\theta + \cos\theta + \cos\theta + \cot\theta \end{bmatrix}$$

$$= 0 + 0 + 0 \qquad 0 + 0 + 0 \qquad 0 + 0 + 0$$

$$A^{T}A = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos^2\theta + \sin^2\theta + 0 & \cos\theta + \sin\theta - \cos\theta & \sin\theta + 0 & \cot\theta \\ \cos\theta + \sin^2\theta + \cos^2\theta + 0 & \cot\theta \\ \cos\theta + \cos\theta + \cos\theta + \cos\theta & \cot\theta \end{bmatrix}$$

.. AAT = ATA = I is a orthogonal

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = T_A, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = A$$

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = TA A$$

TOT I STORY AND A ST A

$$= 1 + 0 = 1$$

$$A^{T}A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

A is an orthogonal Matrix.

Properties of orthogonal matrix # I A is an orthogonal matrix than AT = A-1. * It A is orthogonal, then A is also orthogonal for (A-1)(A-1)T=(A-1)TA-1=I # It A and B are orthogonal, then AB is also orthogonal. for (AB)T = BTAT= (AB)-1. * If A is orthogonal then IAI = ±1 for AAT = I = | AAT | = II) 1 = 1 TA 1 /A 1 4= 1II = 1A1 1A) 1A12 = 1I1

1A12 = 1

1A1 = ± 1

- (91) - TA (01)) - A O

en de administração per de desta entres

* The orthogonal matrix is called a proper orthogonal matrix if IAI=1 and improper orthogonal matrix is

Griven:

* orthogonal matrix

AAT = ATA = I

choose 1st condition.

AAT = I

multiple inverse on both sides-

 $I^{-}A = TAA^{-}A$ $I^{-}A = TA$

AT = 4-1.

 $AT = A^{-1}$ $(A^{-1})T = (A^{-1})^{T} = A$ $(A^{-1})^{T}A^{-1} = X^{-1}(A^{-1})^{T} = I$ $A A^{-1} = A^{-1}A = I$ I = I = I

unitary matrix.

A square matrix A is called a writary matrix it.

 $AA^* = A^*A = I$ (30) A(I) = (30)

Properties of unitary Matrix.

* It A is unitary matrix, then

$$A = A^{-1}$$
 $(ax)^{T} = A^{-1}$

* It A and B are unitary then AB is also unitary.

$$(AB)^{-1} = B^{-1}A^{-1} = (B)^{T}(A)^{T} = (AB)^{T} = (AB)^{T}$$

Express 2 48 as the sum of a

Symmetric and skew - Symmetric Matrix

$$A = \frac{1}{2} (A + A^T)$$

Given:

$$A = \begin{bmatrix} 2 & 4 & 8 \\ 6 & 2 & 8 \\ 2 & 2 & 2 \end{bmatrix}$$

$$A^{\Gamma} = \begin{bmatrix} 2 & b & 2 \\ 4 & 2 & 2 \\ 8 & 8 & 2 \end{bmatrix}$$

TO Prove (A+AT) is symmetric.

$$A + A^{T} = \begin{bmatrix} 2 & 4 & 8 \\ 6 & 2 & 8 \\ 2 & 2 & 2 \end{bmatrix} + \begin{bmatrix} 2 & 6 & 27 \\ 4 & 2 & 2 \\ 8 & 8 & 2 \end{bmatrix}$$

Let
$$B = A + A T$$
 $B = \begin{bmatrix} 1 & 10 & 10 \\ 10 & 4 & 10 \\ 10 & 10 & 4 \end{bmatrix}$
 $B = BT$ Symmetric

Then $CA + AT$) is skew - Symmetric

A - AT = $\begin{bmatrix} 2 & 4 & 8 \\ 6 & 2 & 8 \\ 2 & 2 & 2 \end{bmatrix}$

Let $C = A - AT$
 $C = \begin{bmatrix} 0 & -1 & 6 \\ -2 & 0 & 6 \\ -6 & -6 & 0 \end{bmatrix}$
 $C = -CT$, Skew Symmetria.

 $C = -CT$, Skew Symmetria.

(a) show that the Matrix
$$\frac{2}{3}\begin{bmatrix} 2 & 21 \\ -21 & 2 \end{bmatrix}$$
 is orthogonal.

$$A^{T}A = \frac{1}{3} \begin{bmatrix} 2 & -2 & 1 \\ 2 & 1 & -2 \\ 1 & 2 & 2 \end{bmatrix} \frac{1}{3} \begin{bmatrix} 2 & 2 & 1 \\ -2 & 1 & 2 \\ 1 & -2 & 2 \end{bmatrix}$$

$$= \frac{1}{9} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 &$$

Cof(A) =
$$\begin{bmatrix} \frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ -\frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix}$$

Adj (A) = $\begin{bmatrix} \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix}$

A = $\begin{bmatrix} \frac{1}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix}$

Hence, I, the pallowing matrix is centrary.

This is a prove that the pallowing matrix is centrary.

Gir von:

$$AA^{*} = A^{*}A = I$$

$$AA^{*} = A^{*}A = I$$

$$AA^{*} = \begin{bmatrix} \frac{1-i}{2} & \frac{1-i}{2} \\ \frac{1-i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$AA^{*} = \begin{bmatrix} \frac{1-i}{2} & \frac{1-i}{2} \\ \frac{1-i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$AA^{*} = \begin{bmatrix} \frac{1+i}{2} & \frac{1-i}{2} \\ \frac{1-i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$C(A^{*})(CA^{*}) + (CA^{*})(CA^{*}) + (CA^{*})(CA^{*})$$

$$C(A^{*})(CA^{*}) + (CA^{*})(CA^{*})$$

$$C(A^{*})(CA^{*}) + (CA^{*})(CA^{*})$$

$$C(A^{*})(CA^{*}) + (CA^{*})(CA^{*})$$

$$C(A^{*})(CA^{*}) + (CA^{*})(CA^{*})$$

$$A^{*}A = \begin{bmatrix} \frac{1-i}{2} & \frac{1+i}{2} \\ \frac{1+i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$A^{*}A = \begin{bmatrix} \frac{1-i}{2} & \frac{1+i}{2} \\ \frac{1+i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$A^{*}A = \begin{bmatrix} \frac{1-i}{2} & \frac{1+i}{2} \\ \frac{1+i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$A^{*}A = \begin{bmatrix} \frac{1-i}{2} & \frac{1+i}{2} \\ \frac{1+i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$A^{*}A = \begin{bmatrix} \frac{1-i}{2} & \frac{1+i}{2} \\ \frac{1+i}{2} & \frac{1-i}{2} \end{bmatrix}$$

$$A^{*}A = \begin{bmatrix} \frac{1-i}{2} & \frac{1+i}{2} \\ \frac{1+i}{2} & \frac{1-i}{2} \end{bmatrix}$$

A. is unitary.

Cayley - Hamilton theorem:

characteristic equation of x satisfied

by A. | Ahxin AJin = 0

Explanation:

the characteristic equation $\chi^3 + \alpha_1 \chi^2 + \alpha_2$ the characteristic equation $\chi^3 + \alpha_1 \chi^2 + \alpha_2$ $+ \alpha_3 = 0$. Then $\chi^3 + \alpha_1 \chi^2 + \alpha_2 \chi^2 + \alpha_3 \chi^2 + \alpha_4 \chi^2 + \alpha_5 \chi^2 +$

Example:

Find the characteristic equation of

Griven:

$$A = \begin{bmatrix} 2 & 0 \\ 3 & 2 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} 3 & 0 \\ 3 & 0 \end{bmatrix} - \lambda \begin{bmatrix} 10 \\ 10 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 3 & 2 \end{bmatrix} - \begin{bmatrix} 3 & 0 \\ 0 & \lambda \end{bmatrix}$$

$$\begin{bmatrix} 2-\lambda & 0 \\ 3 & 2-\lambda \end{bmatrix}$$

$$0 = |A - \lambda I| = \begin{vmatrix} 2 - \lambda & 0 \\ 3 & 2 - \lambda \end{vmatrix}$$

$$A^{2} = \begin{bmatrix} 2 & 0 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 12 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 4 & 0 \\ 12 & 4 \end{bmatrix} - 4 \begin{bmatrix} 2 & 0 \\ 3 & 2 \end{bmatrix} + 4 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 & 0 \\ 12 & 4 \end{bmatrix} - \begin{bmatrix} 8 & 0 \\ 12 & 8 \end{bmatrix} + \begin{bmatrix} 4 & 0 \\ 6 & 4 \end{bmatrix}$$

30/06/2

$$A = \begin{bmatrix} 2 & 0 \\ 3 & 2 \end{bmatrix}$$

$$|A| = 4 \quad \frac{1}{4} \begin{bmatrix} 2 & 0 \\ -3 & 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & 0 \\ -3/4 & \frac{1}{2} \end{bmatrix}$$

$$A^{2} - 4/4 + 4/1 = 0$$

$$A^{-1}A^{2} - 4A + 4/1 = 0$$

$$A^{-1}A^{2} - 4A + 4/1 = 0$$

$$A^{-1}AA - 4/1 + 4/1 = 0$$

$$4A - 4/1 + 4/1 = 0$$

$$4A - 4/1 = 4/1 = A$$

$$AA - 4/1 = A$$

$$A$$

(verity cayley's thornaits thamilton theorem for the meetinx $k = \begin{bmatrix} 1 & -1 & 2 \\ -2 & 1 & 3 \\ 3 & 2 & -3 \end{bmatrix}$

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$$A = \begin{bmatrix} 1 & -1 & 2 \\ -2 & 1 & 3 \\ 3 & 2 & -3 \end{bmatrix}$$

$$0 = |A - \lambda I| = \begin{vmatrix} 1 - \lambda & -1 & 2 \\ -2 & 1 - \lambda & 3 \end{vmatrix}$$

$$3 = -3 - \lambda$$

$$0 = (1-\lambda)[(1-\lambda)(-3-\lambda)-6] + 1[-2(-3-\lambda)-6]$$

$$+2[-4-3(1-\lambda)]$$

$$0 = (1-\lambda)[-3-\lambda+3\lambda+\lambda^2-6] + 1[-6+2\lambda-9] + 2[-4-3+3\lambda]$$

$$0 = (1-\lambda)[-9+2\lambda+\lambda^2] + 1[-3+2\lambda] + 2$$

$$[-7+3\lambda]$$

$$0 = -9+2\lambda+\lambda^2+9\lambda-2\lambda^2-\lambda^3-3+2\lambda-4+6\lambda$$

$$0 = -\lambda^3-1\lambda^2+19\lambda-26$$

$$1 = -\lambda^3-1\lambda^2+19\lambda-26$$

$$1 = -\lambda^3+\lambda^2-19\lambda+26=0$$

$$1 = -\lambda^3+\lambda^2-19\lambda+26=0$$

$$1 = -\lambda^3+\lambda^2-19\lambda+26=0$$

$$1 = -\lambda^3-16$$

$$1 = -\lambda$$

PARL CX + FA

 $A^{3} - 3A^{2} - A + 9I = 0$ $A^{2} - 3A - I + 9A^{-1} = 0$ $9A^{-1} = A^{2} + 3A - I$

$$A = \begin{bmatrix} 1 & 0 & 3 \\ 2 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -3 & 6 & 1 \\ 3 & 2 & 4 \\ 0 & -2 & 5 \end{bmatrix}$$

$$3 A = 3 \begin{bmatrix} 3 & 0 & 0 \\ 3 & -3 & 3 \\ 0 & -3 & 3 \end{bmatrix}$$

$$9 A^{-1} = -A = A = A + A + A$$

$$3 A = 3 \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & 3 \end{bmatrix}$$

$$-1 A = \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & 3 \end{bmatrix}$$

$$-1 A = \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

$$-1 A = \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

$$3 A = 3 \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

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$$3 A = 3 \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

$$4 A = \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

$$3 A = 3 \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

$$3 A = 3 \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

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$$3 A = 3 \begin{bmatrix} 1 & 0 & 3 \\ 3 & -1 & 1 \\ 0 & -3 & -2 \end{bmatrix}$$

Outing cayley hamilton theorem; find

At given that
$$h = \begin{bmatrix} 2 & -2 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

Chiven:

$$A = \begin{bmatrix} 2 & -2 & 1 \\ 0 & 1 & 2 \end{bmatrix} = 0$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} 0-2 \end{bmatrix} + \begin{bmatrix} (1-\lambda) \end{bmatrix} = 0$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} 0-2 \end{bmatrix} + \begin{bmatrix} (1-\lambda) \end{bmatrix} = 0$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} 0-2 \end{bmatrix} + \begin{bmatrix} (1-\lambda) \end{bmatrix} = 0$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda) \end{bmatrix} = 0$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix}$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix}$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix}$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix}$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix}$$

$$(2-\lambda) \begin{bmatrix} (1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-\lambda)(1-\lambda)(1-\lambda) - 0 \end{bmatrix} + 2 \begin{bmatrix} (1-$$

$$E = \begin{bmatrix} 60 & -72 & -12 \\ -12 & 46 \\ -14 & 24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & 0 & 19 \\ -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & 0 & 19 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -19 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & 5 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \end{bmatrix} = \begin{bmatrix} 12 & 0 & 0 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 & -24 & -24 & -24 \\ -24 &$$

(a) =
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